

# Contractor

`Contractor[form, vector]`  
represents the contraction of a vector on a form.

## Details

- On output Contractors are formatted as PineGreen AngleBrackets.
- A Contractor template is on the × tab of the Common Operations palette.
- A Contractor requires both 1-form and 1-vector elements but you can only be in one of the bases at a time. Nevertheless, the Grassmann Symbols palette will allow you to paste both types of elements and you can easily type the form symbols.
- Note that the first slot always contains an m-form and the second slot a k-vector. The result of evaluation will be zero unless  $m \geq k$ . If the k-vector is within the form the result of evaluation will be an (m-k)-form.
- Essentially, a form "measures" the vector. If the vector doesn't "fit" into the form the result is zero.
- A `LeftContractor` is equivalent to a `Contractor`. A `RightContractor` will sometimes give a different sign.  
 $\text{RightContractor} = (-1)^{\text{Grade}[\text{vector}]} (\text{Grade}[\text{form}] - \text{Grade}[\text{vector}]) \text{LeftContractor}$ .
- The form and vector symbols are available on a current `GrassmannSymbolsPalette`.
- A Contractor should be distinguished from an uncolored AngleBracket, also used in Grassmann Algebra to represent the coefficient of a general n-element in the unit n-element.

## Examples (5)

### Basic Examples (1)

See below for a general overview of the contraction routines

```
In[1]:= << GrassmannCalculus`
```

```
In[2]:= SetActiveAssociation[PublicGrassmannAtlas["Euclidean 3-Space"]]
```

A Contractor can be entered as a plain expression or from the palette. `ContractorRules` evaluates scalar contractors.

```
In[3]:= {Contractor[dx, e_x], <dx, e_x>}
% /. ContractorRules[]
```

```
Out[3]= {<dx, e_x>, <dx, e_x>}
```

```
Out[3]= {1, 1}
```

General exterior elements can be entered.

```
In[4]:= <1 + dx + dx ^ dy + dx ^ dy ^ dz, a e_x + b e_x ^ e_y ^ e_z>
% // EvaluateContractors
Out[4]= <1 + dx + dx ^ dy + dx ^ dy ^ dz, a e_x + b e_x ^ e_y ^ e_z>

Out[4]= a + b + a dy + a dy ^ dz
```

A `LeftContractor` is equivalent to a `Contractor`. A `RightContractor` may give a change of sign.

```
In[5]:= {<dx ^ dy, e_x>, e_x ↦ dx ^ dy, dx ^ dy ↦ e_x}
% // EvaluateContractors
Out[5]= {<dx ^ dy, e_x>, e_x ↦ dx ^ dy, dx ^ dy ↦ e_x}

Out[5]= {dy, dy, -dy}
```

#### General Overview of Contraction Routines (4)

Set 6-dimensional Euclidean space.

```
In[33]:= SetEuclideanNSpace[6, {u, v, w, x, y, z}, "Vector"]
**S[a, b, c, d]
```

The following are contractions of a 1-vector on a 1-form, which results in a scalar.

```
In[35]:= {<du, e_u>, <du, e_v>}
% // EvaluateContractors
Out[35]= {<du, e_u>, <du, e_v>}

Out[36]= {1, 0}
```

The following can be evaluated directly or expanded first and evaluated with rules.

```
In[37]:= <a dx + b dy, c e_x + d e_y>
% // EvaluateContractors
Out[37]= <a dx + b dy, c e_x + d e_y>

Out[38]= a c + b d

In[51]:= <a dx + b dy, c e_x + d e_y>
% // GrassmannBreakout[Contractor, All]
% // EvaluateContractors
Out[51]= <a dx + b dy, c e_x + d e_y>

Out[52]= a c <dx, e_x> + a d <dx, e_y> + b c <dy, e_x> + b d <dy, e_y>

Out[53]= a c + b d
```

Grassmann interior products can usually be evaluated faster by evaluating with `ContractInteriorProducts`, which converts them to `Contractors` using the metric.

```
In[72]:= (e_z ^ (a e_x + b e_y)) @ (c e_x + d e_y)
% // ToMetricElements // Simplify // Timing
%% // ContractInteriorProducts // Timing
```

```
Out[72]= e_z ^ (a e_x + b e_y) @ (c e_x + d e_y)
```

```
Out[73]= {0.312002, -(a c + b d) e_z}
```

```
Out[74]= {0.0468003, -(a c + b d) e_z}
```

`Contractors` don't require the use of a metric. (A metric is required to convert between forms and vectors and between interior products and `Contractors`.) Without a metric, `Contractors` can be evaluated by reducing them to scalar `Contractors` and using `ContractorRules`. These are equivalent to Kronecker delta on the dual elements.

```
In[24]:= ContractorRules[]
```

```
Out[24]= { {<du, e_u> -> 1, <du, e_v> -> 0, <du, e_w> -> 0, <du, e_x> -> 0, <du, e_y> -> 0, <du, e_z> -> 0,
  <dv, e_u> -> 0, <dv, e_v> -> 1, <dv, e_w> -> 0, <dv, e_x> -> 0, <dv, e_y> -> 0, <dv, e_z> -> 0,
  <dw, e_u> -> 0, <dw, e_v> -> 0, <dw, e_w> -> 1, <dw, e_x> -> 0, <dw, e_y> -> 0, <dw, e_z> -> 0,
  <dx, e_u> -> 0, <dx, e_v> -> 0, <dx, e_w> -> 0, <dx, e_x> -> 1, <dx, e_y> -> 0, <dx, e_z> -> 0,
  <dy, e_u> -> 0, <dy, e_v> -> 0, <dy, e_w> -> 0, <dy, e_x> -> 0, <dy, e_y> -> 1, <dy, e_z> -> 0,
  <dz, e_u> -> 0, <dz, e_v> -> 0, <dz, e_w> -> 0, <dz, e_x> -> 0, <dz, e_y> -> 0, <dz, e_z> -> 1}
```

```
In[75]:= <a dx + b dy, c e_x + d e_y>
% // GrassmannBreakout[Contractor, All]
% /. ContractorRules[]
```

```
Out[75]= <a dx + b dy, c e_x + d e_y>
```

```
Out[76]= a c <dx, e_x> + a d <dx, e_y> + b c <dy, e_x> + b d <dy, e_y>
```

```
Out[77]= a c + b d
```

---

Higher order inner product contraction.

```
In[1]:= <a dx ^ dy, b e_x ^ e_y>
% // EvaluateContractors
```

```
Out[1]= <a dx ^ dy, b e_x ^ e_y>
```

```
Out[1]= a b
```

In the following the vector is not contained in the form because  $e_u$  is not in the space of the form. The result is zero.

```
In[2]:= b e_u ^ e_v -> a dx ^ dv
% // EvaluateContractors
```

```
Out[2]= b e_u ^ e_v -> a dx ^ dv
```

```
Out[2]= 0
```

---

Contracting different grade elements

```
In[1]:= e_u ^ e_w -> du ^ dv ^ dw
% // EvaluateContractors
```

```
Out[1]= e_u ^ e_w -> du ^ dv ^ dw
```

```
Out[1]= -dv
```

Using more general Grassmann elements.

```
In[2]:= <a du ^ dv ^ dw + b du ^ dx, c e_u + d e_x>
% // EvaluateContractors
```

```
Out[2]= <b du ^ dx + a du ^ dv ^ dw, c e_u + d e_x>
```

```
Out[2]= -b d du + b c dx + a c dv ^ dw
```

```
In[3]:= <1 + dx + dx ^ dy + dx ^ dy ^ dz, 5 + a e_x + b e_x ^ e_y ^ e_z>
% // EvaluateContractors
```

```
Out[3]= <1 + dx + dx ^ dy + dx ^ dy ^ dz, 5 + a e_x + b e_x ^ e_y ^ e_z>
```

```
Out[3]= 5 + a + b + 5 dx + a dy + 5 dx ^ dy + a dy ^ dz + 5 dx ^ dy ^ dz
```

A larger vector space contracts to zero on a smaller form space.

```
In[4]:= e_u ^ e_v ^ e_w ↦ du
% // EvaluateContractors
```

```
Out[4]= e_u ^ e_v ^ e_w ↦ du
```

```
Out[4]= 0
```

Spacetime contractions

```
In[1]:= SetActiveAssociation[PublicGrassmannAtlas[["Minkowski Space"]]]
**S[m, vx, vy, vz]; *V[{}];
```

Writing the momentum of a particle  $p$  in terms of it's spatial velocity  $v$ .

```
In[2]:= v = {vx, vy, vz}.Drop[VectorBasis, 1]
p =  $\frac{m}{\sqrt{1 - v \Theta v}}$  (e_t + v)
```

```
Out[2]= vx e_x + vy e_y + vz e_z
```

```
Out[2]=  $\frac{m (e_t + vx e_x + vy e_y + vz e_z)}{\sqrt{1 - (vx e_x + vy e_y + vz e_z) \Theta (vx e_x + vy e_y + vz e_z)}}$ 
```

The square of the Measure, or spacetime interval is:

```
In[3]:= p \Theta p // ToMetricElements // Timing
```

```
Out[3]= {1.13881, -m^2}
```

This can also be calculated somewhat faster in the Contractor formalism as:

```
In[4]:= (p = p // ContractInteriorProducts) // Timing
p ↦ (p /. VectorToForm)
% // EvaluateContractors // Simplify // Timing
```

```
Out[4]= {0.0156001,  $\frac{m (e_t + vx e_x + vy e_y + vz e_z)}{\sqrt{1 - vx^2 - vy^2 - vz^2}}$ }
```

```
Out[4]=  $\frac{m (e_t + vx e_x + vy e_y + vz e_z)}{\sqrt{1 - vx^2 - vy^2 - vz^2}} \mapsto \frac{m (-dt + dx vx + dy vy + dz vz)}{\sqrt{1 - vx^2 - vy^2 - vz^2}}$ 
```

```
Out[4]= {0.156001, -m^2}
```

Notice that `VectorToForm` uses the metric, as did `ContractInteriorProducts`.

```
In[5]:= VectorToForm
```

```
Out[5]= {et → -dt, ex → dx, ey → dy, ez → dz}
```

---

#### See Also

**LeftContractor** · **RightContractor** · **ConvertToContractor** · **ContractorRules** · **ToScalarContractor** · **EvaluateContractors** · **ContractInteriorProducts** · **FormBasis** · **VectorBasis**

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#### Related Guides

- [Contractors](#)
- [Derivatives](#)
- [Grassmann Calculus](#)